

EIE209 Basic Electronics

# Basic circuit analysis

# Fundamental quantities

**Voltage** — potential difference bet. 2 points

“across” quantity

analogous to ‘pressure’ between two points

**Current** — flow of charge through a material

“through” quantity

analogous to fluid flowing along a pipe

$$I = \lim_{\delta t \rightarrow 0} \frac{\delta q}{\delta t} = \frac{dq}{dt}$$

# Units of measurement

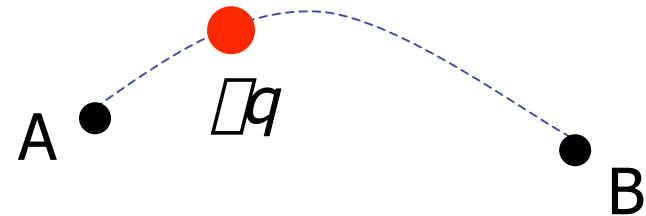
- Voltage: volt (V)
- Current: ampere (A)
- **NOT Volt, Ampere!!**

Prefix	Multiplier (abbreviation)
Peta	$\times 10^{15}$ (P)
Tera	$\times 10^{12}$ (T)
Giga	$\times 10^9$ (G)
Mega	$\times 10^6$ (M)
Kilo	$\times 10^3$ (k)
Hecto	$\times 10^2$ (h)
Deca	$\times 10$ (da)
deci	$\times 10^{-1}$ (d)
centi	$\times 10^{-2}$ (c)
milli	$\times 10^{-3}$ (m)
micro	$\times 10^{-6}$ ( $\mu$ )
nano	$\times 10^{-9}$ (n)
pico	$\times 10^{-12}$ (p)
femto	$\times 10^{-15}$ (f)

# Power and energy

**Work done** in moving a charge  $\Delta q$  from A to B having a potential difference of  $V$  is

$$W = V \Delta q$$

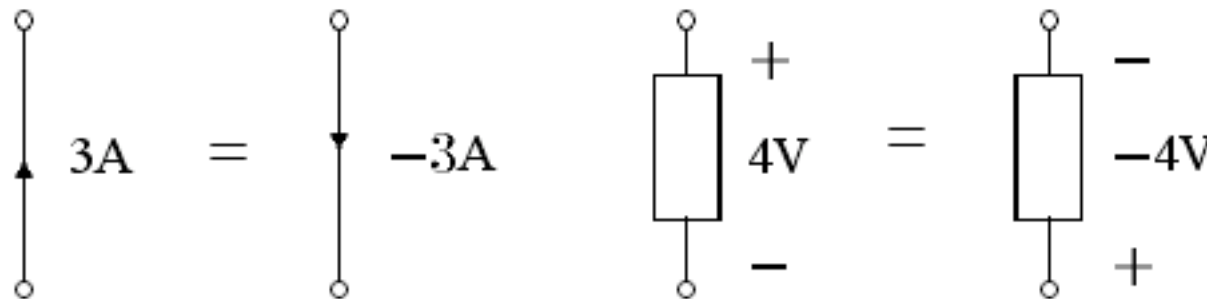


**Power** is work done per unit time, i.e.,

$$P = \lim_{\delta t \rightarrow 0} V \frac{\delta q}{\delta t} = V \frac{dq}{dt} = VI$$

# Direction and polarity

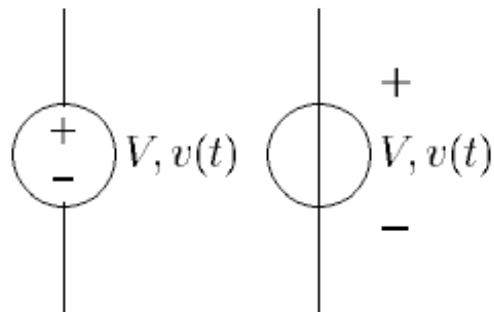
- Current direction indicates the direction of flow of positive charge
- Voltage polarity indicates the relative potential between 2 points:  
+ assigned to a higher potential point; and - assigned to a lower potential point.
- *NOTE: Direction and polarity are arbitrarily assigned on circuit diagrams. Actual direction and polarity will be governed by the sign of the value.*



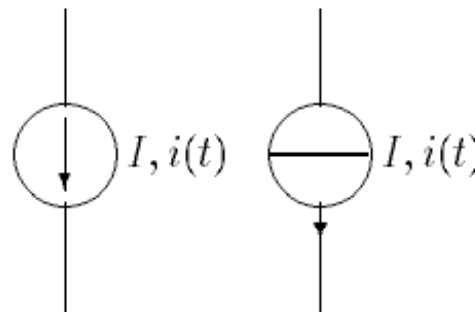
# Independent sources

- Voltage sources
- Current sources

Independent — stubborn! never change!



Independent  
voltage source



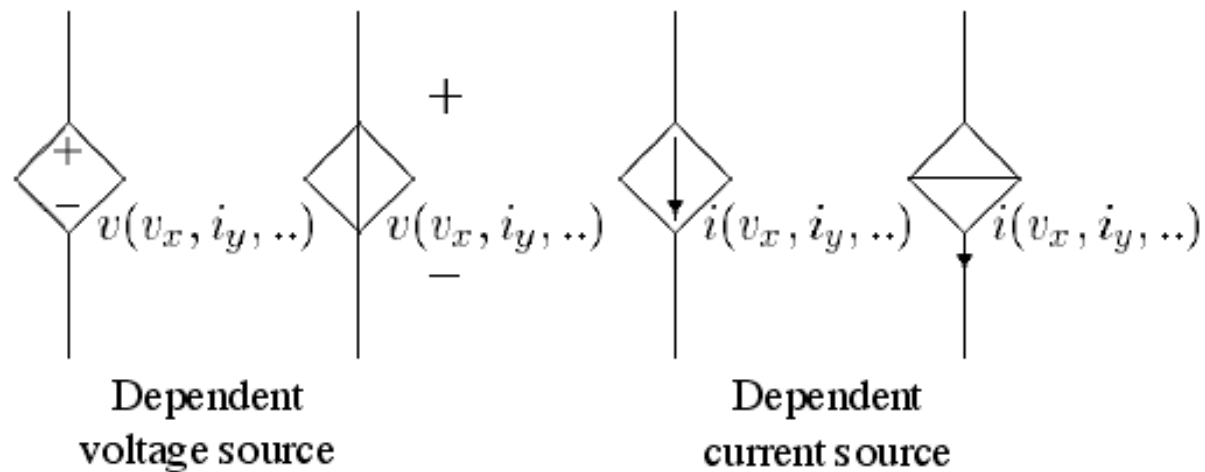
Independent  
current source

Maintains a  
voltage/current  
(fixed or varying)  
which is not  
affected by any  
other quantities.

An independent voltage source can never be shorted.  
An independent current source can never be opened.

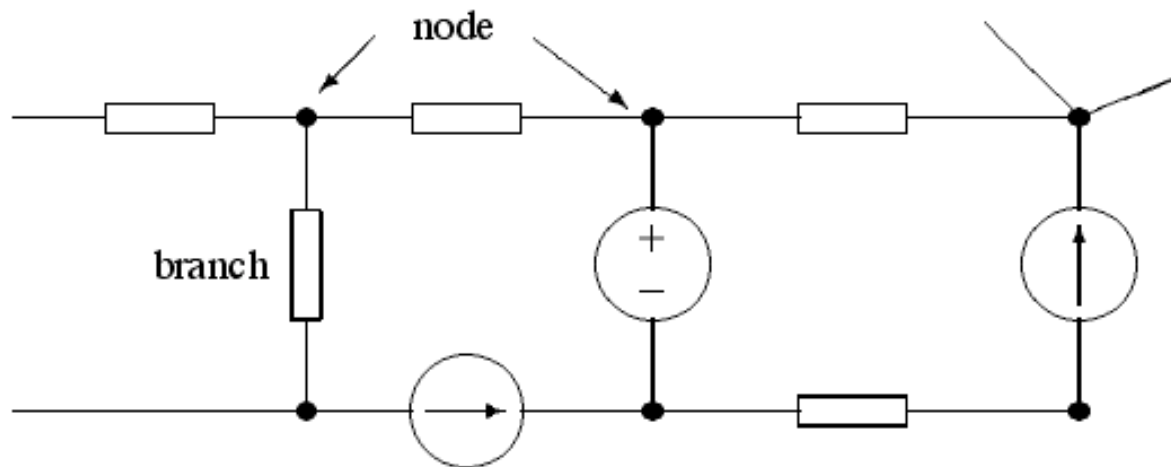
# Dependent sources

- Dependent sources — values depend on some other variables



# Circuit

- Collection of devices such as sources and resistors in which terminals are connected together by conducting wires.
  - These wires converge in **NODES**
  - The devices are called **BRANCHES** of the circuit



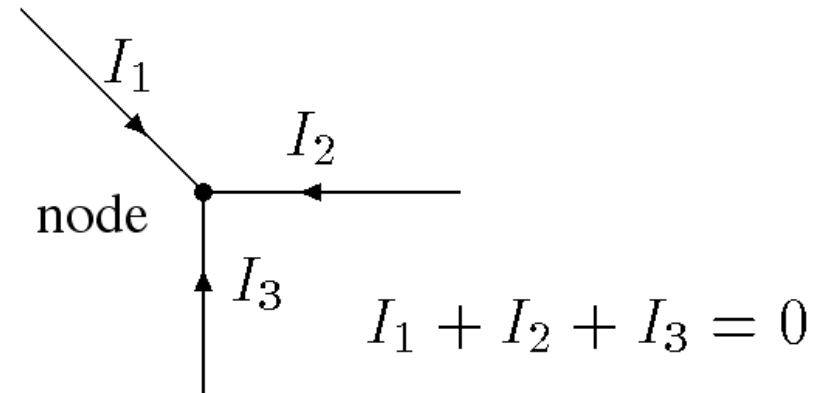
Circuit Analysis Problem:  
To find all currents and voltages in the branches of the circuit when the intensities of the sources are known.



# Kirchhoff's laws

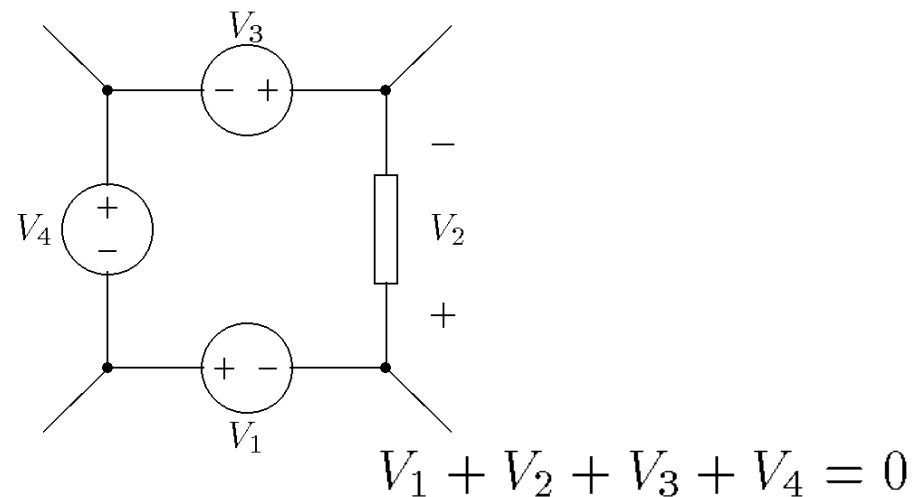
- Kirchhoff's current law (KCL)

- The algebraic sum of the currents in all branches which converge to a common node is equal to zero.



- Kirchhoff's voltage law (KVL)

- The algebraic sum of all voltages between successive nodes in a closed path in the circuit is equal to zero.



# Overview of analysis

- Ad hoc methods (not general)

- Series/parallel reduction
- Ladder circuit
- Voltage/current division
- Star-delta conversion

- More general

- Mesh and nodal methods

- Completely general

- Loop and cutset approach (requires graph theory)

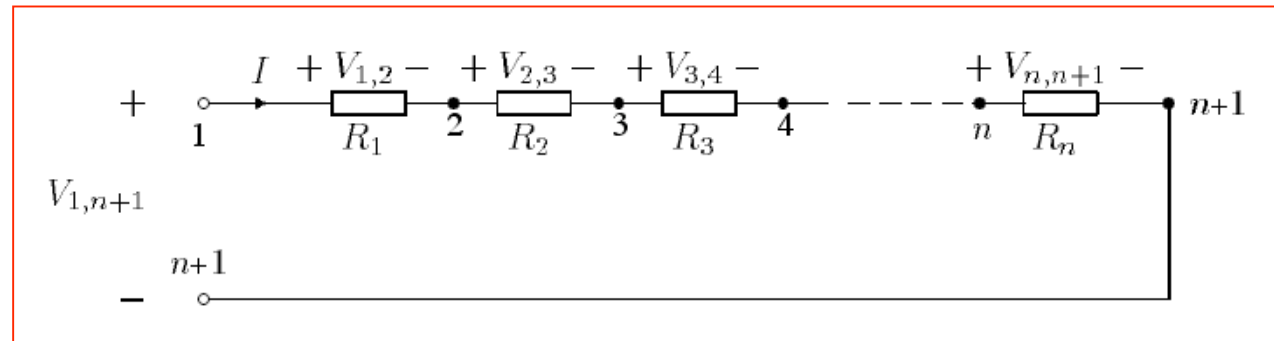


**Done in  
Basic  
Electronics!**

**NEW**

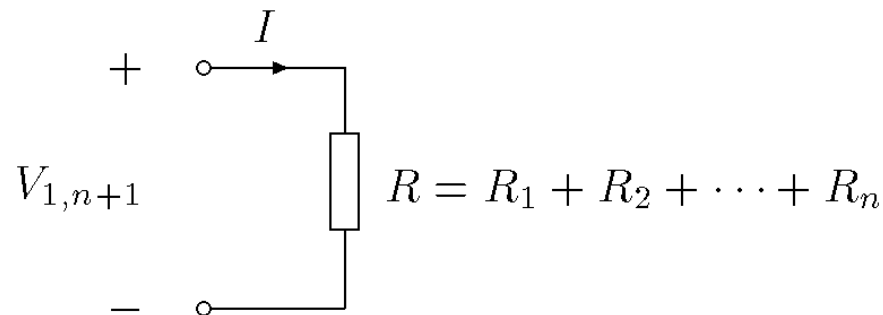
# Series/parallel reduction

- **Series circuit**— each node is incident to just two branches of the circuit



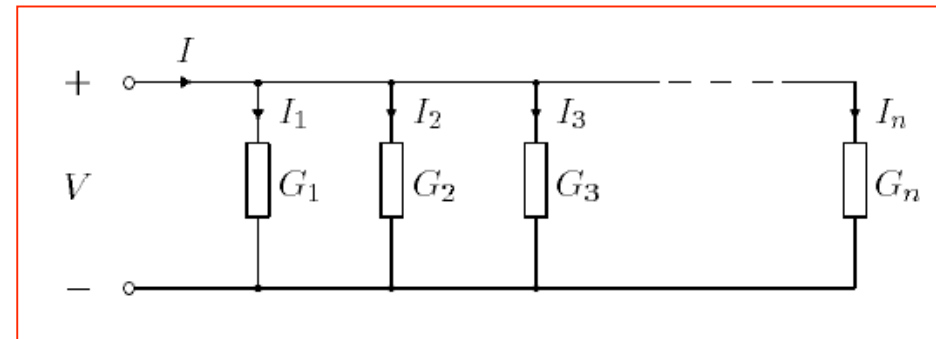
$$\begin{aligned} \text{KVL gives } V_{1,n+1} &= V_{12} + V_{23} + \cdots + V_{n,n+1} \\ &= (R_1 + R_2 + \cdots + R_n)I \end{aligned}$$

Hence, the equivalent resistance is:



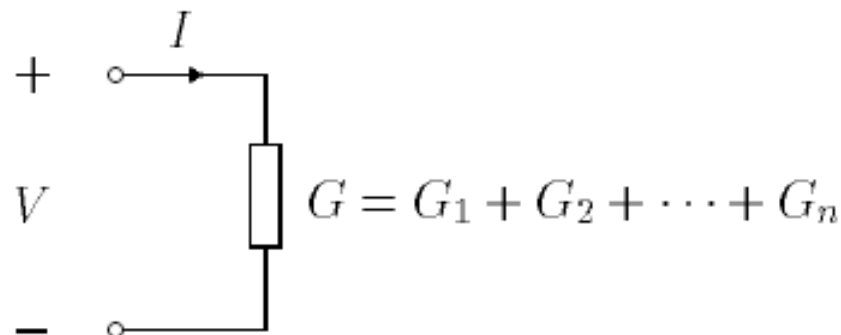
# Series/parallel reduction

- **Parallel circuit**— one terminal of each element is connected to a node of the circuit while other terminals of the elements are connected to another node of the circuit



KCL gives 
$$I = (G_1 + G_2 + \cdots + G_n)V$$

Hence, the equivalent resistance is:



# Note on algebra

- For algebraic brevity and simplicity:
  - For series circuits, R is preferably used.
  - For parallel circuits, G is preferably used.

For example, if we use R for the parallel circuit, we get the equivalent resistance as

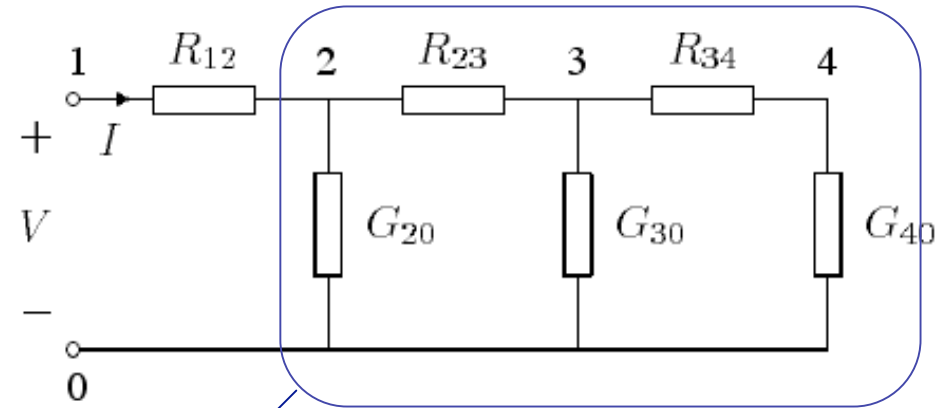
$$R = \frac{R_1 R_2 R_3 \cdots R_n}{R_2 R_3 \cdots R_n + R_1 R_3 R_4 \cdots R_n + \cdots + R_1 R_2 \cdots R_{n-1}}$$

which is more complex than the formula in terms of G:

$$G = G_1 + G_2 + \dots + G_n$$

# Ladder circuit

- We can find the resistance looking into the terminals 0 and 1, by apply the series/parallel reduction successively.



First, lumping everything beyond node 2 as  $G_2$ , we have  $\frac{V}{I} = R_{12} + \frac{1}{G_2}$

Then, we focus on this  $G_2$ , which is just  $G_{20}$  in parallel with another subcircuit, i.e.,

$$G_2 = G_{20} + \frac{1}{R'_2}$$

We continue to focus on the remaining subcircuit. Eventually we get

$$\frac{V}{I} = R_{12} + \frac{1}{G_{20} + \frac{1}{R_{23} + \frac{1}{G_{30} + \frac{1}{R_{34} + \frac{1}{G_{40}}}}}}$$

# Voltage/current division

For the series circuit, we can find the voltage across each resistor by the formula:

$$V_{i,i+1} = R_i I = \frac{R_i V}{R_1 + R_2 + \cdots + R_n}$$

For the parallel circuit, we can find the current through each resistor by the formula:

$$I_i = G_i V = \frac{G_i I}{G_1 + G_2 + \cdots + G_n}$$

Note the choice of R and G in the formulae!

# Example (something that can be done with series/parallel reduction)

Consider this circuit, which is created deliberately so that you can solve it using series/parallel reduction technique. **Find  $V_2$ .**

Solution:

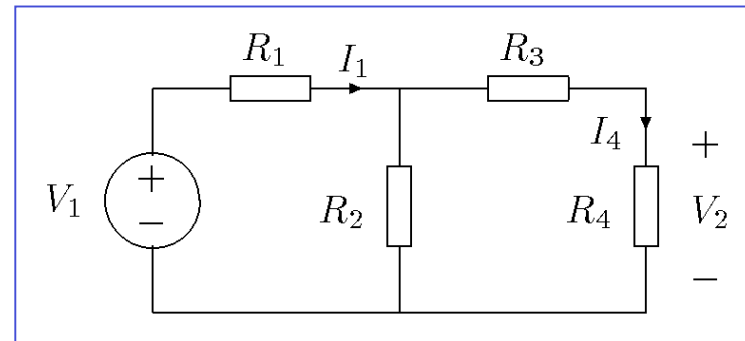
Resistance seen by the voltage source is

$$R = \frac{V_1}{I_1} = R_1 + \frac{1}{\frac{1}{R_2} + \frac{1}{R_3 + R_4}} = R_1 + \frac{R_2(R_3 + R_4)}{R_2 + R_3 + R_4}$$

Hence, 
$$I_1 = \frac{(R_2 + R_3 + R_4)V_1}{(R_3 + R_4)(R_1 + R_2) + R_1R_2}$$

Current division gives:

$$I_4 = I_1 \times \frac{\left(\frac{1}{R_3 + R_4}\right)}{\left(\frac{1}{R_3 + R_4}\right) + \frac{1}{R_2}} = \frac{R_2 I_1}{R_2 + R_3 + R_4}$$



Then, using  $V_2 = I_4 R_4$ , we get

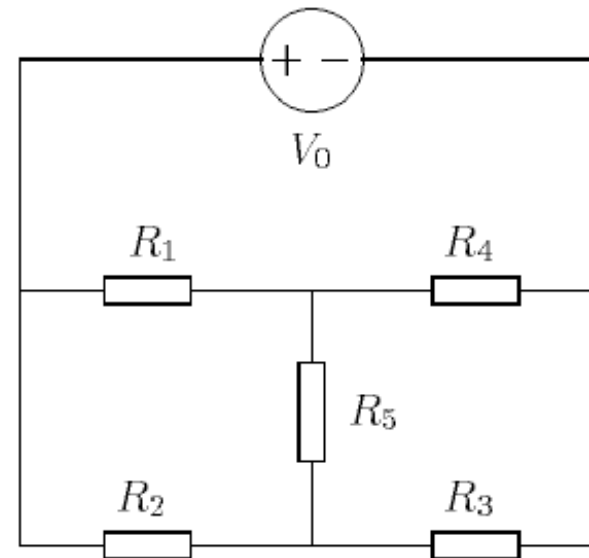
$$V_2 = \frac{R_2 R_4 V_1}{(R_1 + R_2)(R_3 + R_4) + R_1 R_2}$$



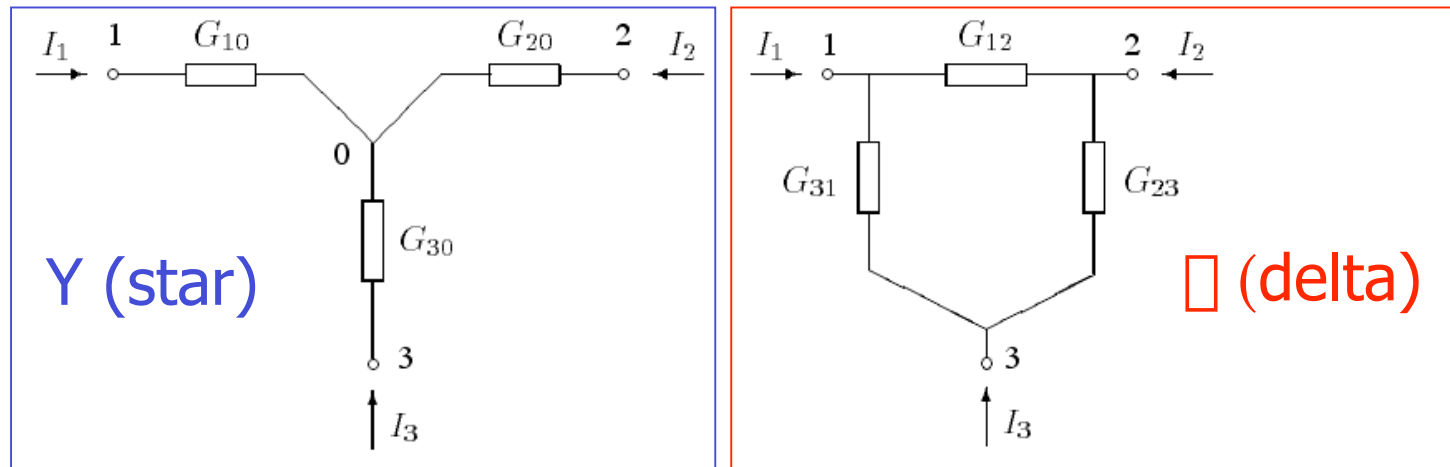
# Oops!

Series/parallel reduction  
*fails* for this bridge circuit!

Is there some *ad hoc*  
solution?



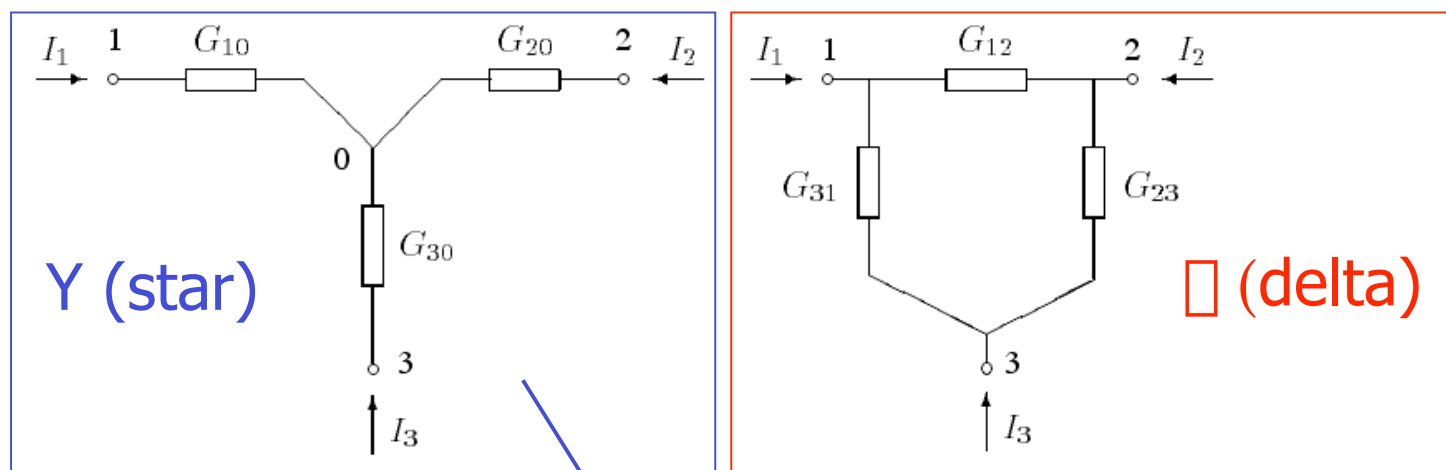
# Equivalence of star and delta



## Problems:

1. Given a star circuit, find the delta equivalence. That means, suppose you have all the  $G$ 's in the star. Find the  $G$ 's in the delta such that the two circuits are "equivalent" from the external viewpoint.
2. The reverse problem.

# Star-to-delta conversion



**For the Y circuit,** we consider summing up all currents into the centre node:  $I_1 + I_2 + I_3 = 0$ , where

$$I_1 = G_{10}(V_1 - V_0)$$

$$I_2 = G_{20}(V_2 - V_0)$$

$$I_3 = G_{30}(V_3 - V_0)$$

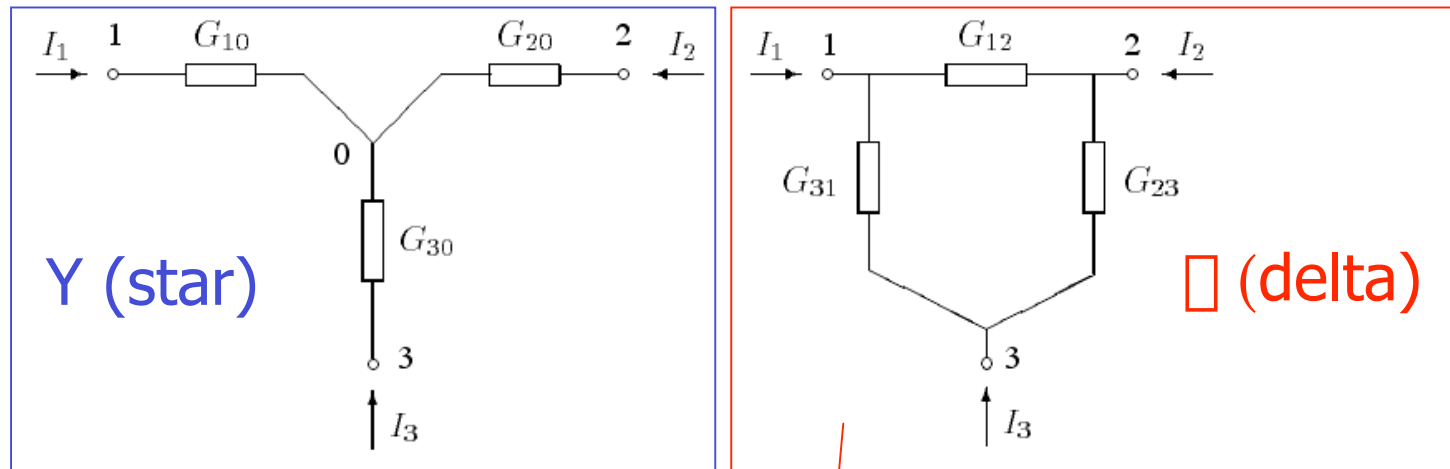
Thus,  $V_0 = \frac{G_{10}V_1 + G_{20}V_2 + G_{30}V_3}{G_{10} + G_{20} + G_{30}}$ , and

$$I_1 = \frac{(G_{20} + G_{30})V_1 - G_{20}V_2 - G_{30}V_3}{G_{10} + G_{20} + G_{30}} \times G_{10}$$

$$I_2 = \frac{-G_{10}V_1 + (G_{30} + G_{10})V_2 - G_{30}V_3}{G_{10} + G_{20} + G_{30}} \times G_{20}$$

$$I_3 = \frac{-G_{10}V_1 - G_{20}V_2 + (G_{10} + G_{20})V_3}{G_{10} + G_{20} + G_{30}} \times G_{30}$$

# Star-to-delta conversion



For the  $\Delta$  circuit, we have

$$\begin{aligned} I_1 &= (G_{12} + G_{31})V_1 - G_{12}V_2 - G_{31}V_3 \\ I_2 &= -G_{12}V_1 + (G_{12} + G_{23})V_2 - G_{23}V_3 \\ I_3 &= -G_{31}V_1 - G_{23}V_2 + (G_{31} + G_{23})V_3 \end{aligned}$$

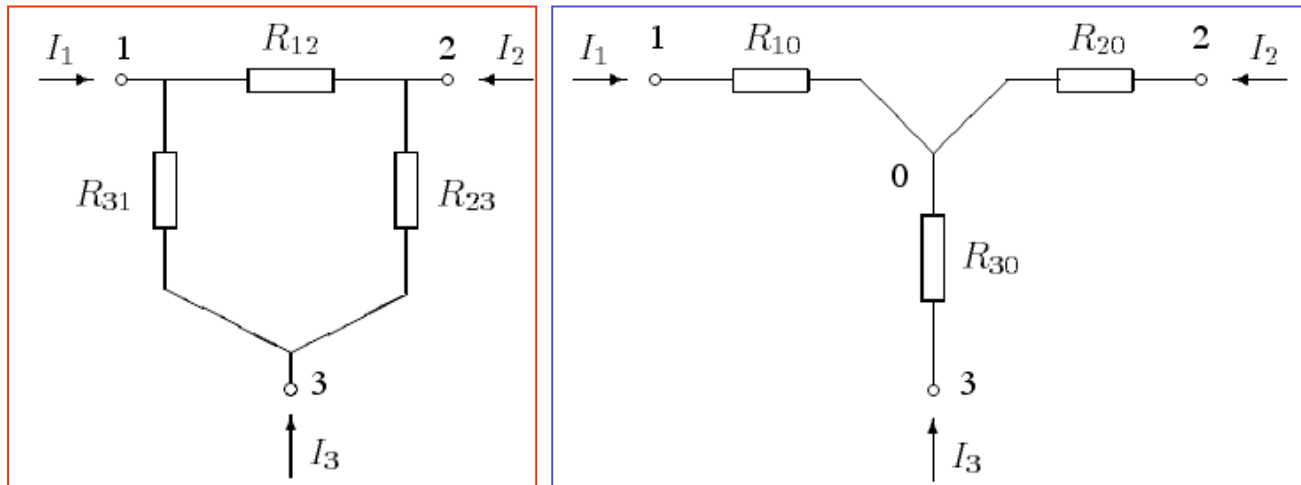
# Star-to-delta conversion

Now, equating the two sets of  $I_1$ ,  $I_2$  and  $I_3$ , we get

$$G_{12} = \frac{G_{10}G_{20}}{G_{10} + G_{20} + G_{30}}$$
$$G_{23} = \frac{G_{20}G_{30}}{G_{10} + G_{20} + G_{30}}$$
$$G_{31} = \frac{G_{10}G_{30}}{G_{10} + G_{20} + G_{30}}$$

The first problem is solved.

# Delta-to-star conversion



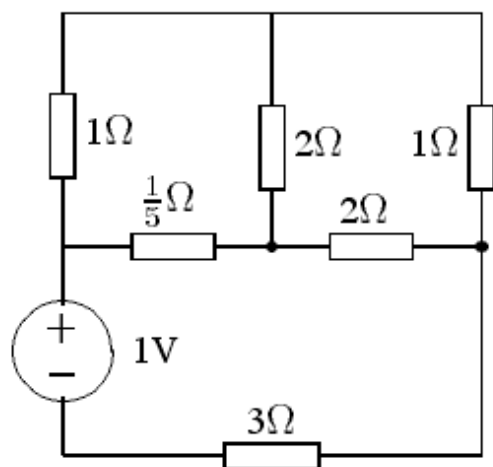
This problem is more conveniently handled in terms of R. The answer is:

$$R_{10} = \frac{R_{12}R_{31}}{R_{23} + R_{31} + R_{12}}$$

$$R_{20} = \frac{R_{23}R_{12}}{R_{23} + R_{31} + R_{12}}$$

$$R_{30} = \frac{R_{31}R_{23}}{R_{23} + R_{31} + R_{12}}$$

## Example — the bridge circuit again

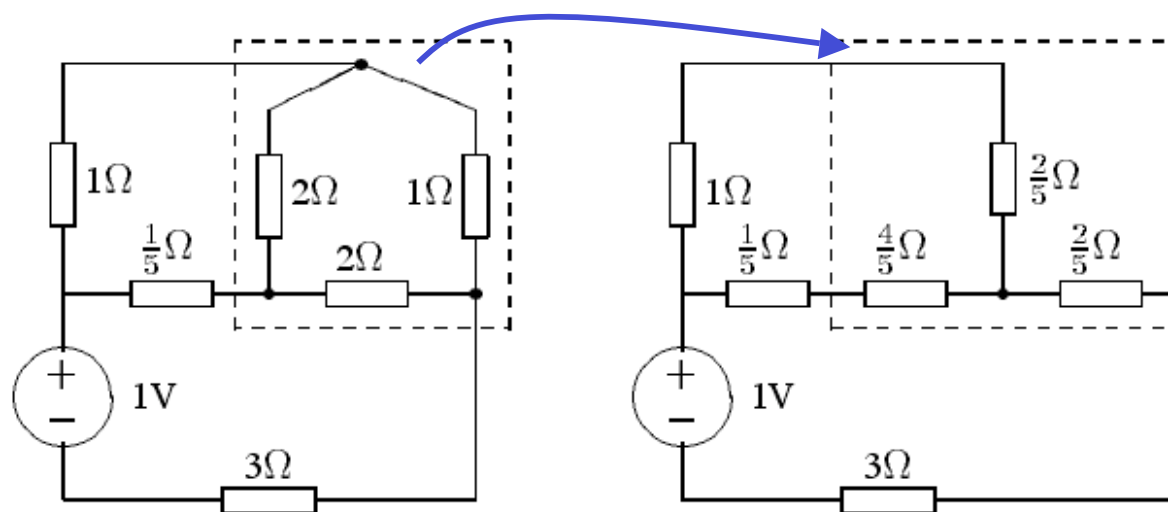


We know that the series/parallel reduction method is not useful for this circuit!

The star-delta transformation may solve this problem.

The question is how to apply the transformation so that the circuit can become solvable using the series/parallel reduction or other ad hoc methods.

## Example — the bridge circuit again



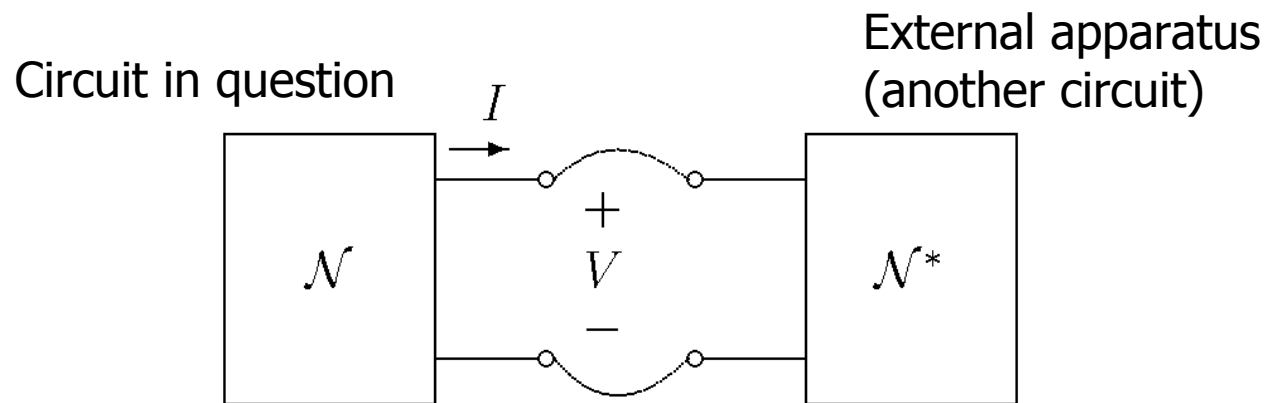
After we do the conversion from Y to D, we can easily solve the circuit with parallel/series reduction.



# Useful/important theorems

- Thévenin Theorem
- Norton Theorem
- Maximum Power Transfer Theorem

# Thévenin and Norton theorems



## Problem:

Find the simplest equivalent circuit model for  $\mathcal{N}$ , such that the external circuit  $\mathcal{N}^*$  would not feel any difference if  $\mathcal{N}$  is replaced by that equivalent model.

The solution is contained in two theorems due to Thévenin and Norton.

# Thévenin and Norton theorems

Let's look at the logic behind these theorems (quite simple really).

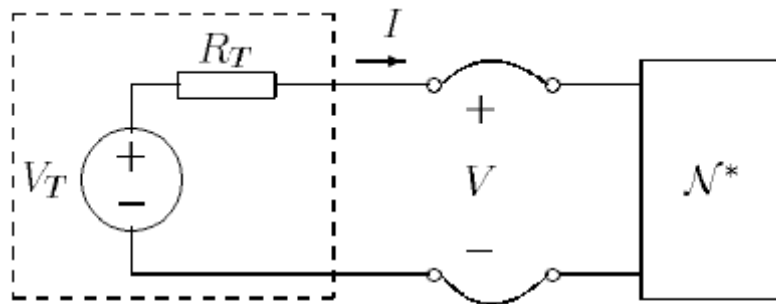
If we write down KVL, KCL, and Ohm's law equations correctly, we will have **a number of equations with the same number of unknowns**. Then, we can try to solve them to get what we want.

Now suppose everything is linear. We are sure that we can get the following equation after elimination/substitution (some high school algebra):

$$aV + bI - c = 0$$

Case 1: $a \neq 0$	$V = \frac{-b}{a}I + \frac{c}{a} = -R_T I + V_T$	→ Thévenin
Case 2: $b \neq 0$	$I = \frac{-a}{b}V + \frac{c}{b} = -\frac{V}{R_N} + I_N$	→ Norton

# Equivalent models

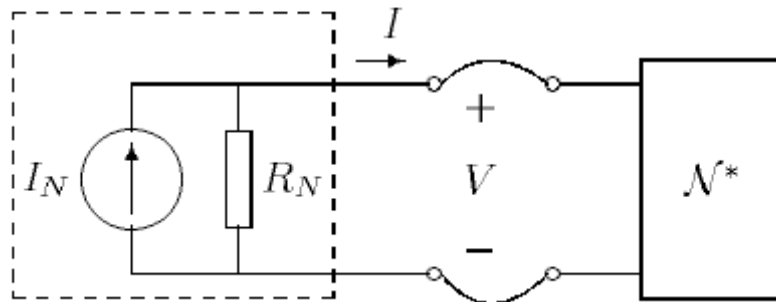


Thévenin equiv. ckt

Voltage source in series with a resistor

$$\text{i.e., } V + IR_T = V_T$$

which is consistent with case 1 equation



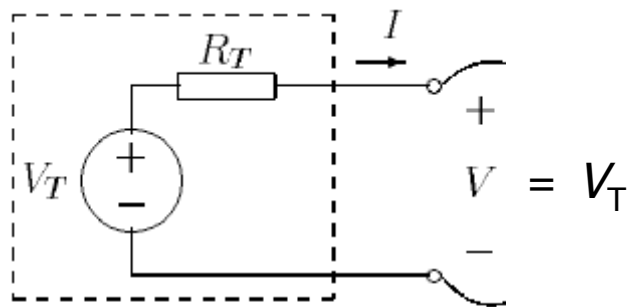
Norton equiv. ckt

Current source in parallel with a resistor

$$\text{i.e., } I = I_N + V/R_N$$

which is consistent with case 2 equation

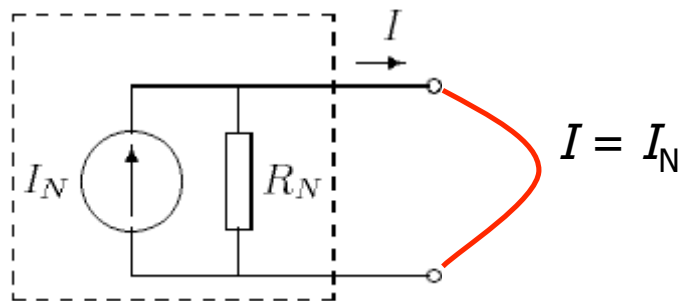
# How to find $V_T$ and $I_N$



Thévenin equiv. ckt

Open-circuit the terminals ( $I=0$ ), we get  $V_T$  as the observed value of  $V$ .

Easy!  $V_T$  is just the open-circuit voltage!

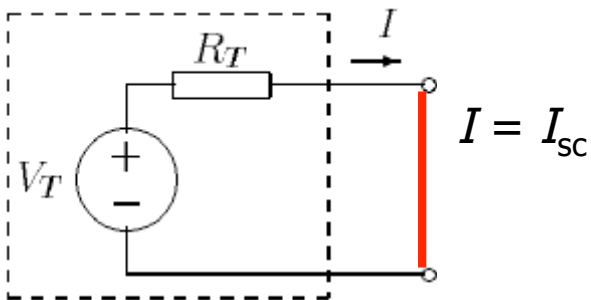


Norton equiv. ckt

Short-circuit the terminals ( $V=0$ ), we get  $I_N$  as the observed current  $I$ .

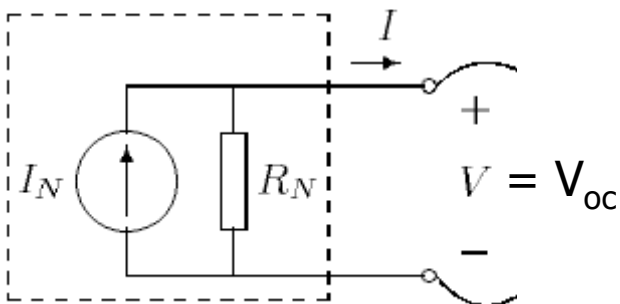
Easy!  $I_N$  is just the short-circuit current!

## How to find $R_T$ and $R_N$ (they are equal)



Thévenin equiv. ckt

Short-circuit the terminals ( $V=0$ ), find  $I$  which is equal to  $V_T/R_T$ . Thus,  $R_T = V_T / I_{sc}$



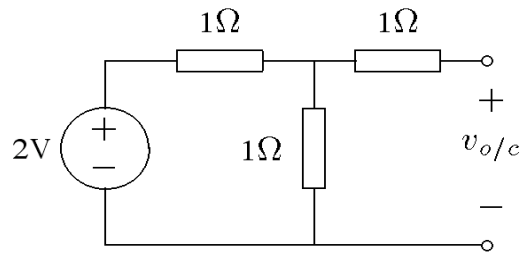
Norton equiv. ckt

Open-circuit the terminals ( $I=0$ ), find  $V$  which is equal to  $I_N R_N$ . Thus,  $R_N = V_{oc} / I_N$ .

For both cases,

$$R_T = R_N = V_{oc} / I_{sc}$$

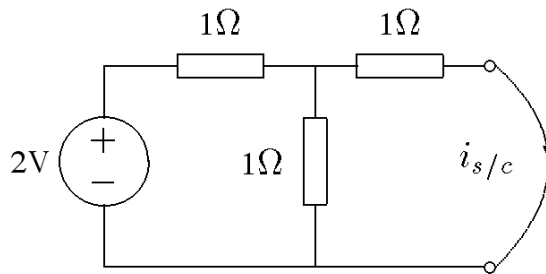
# Simple example



Step 1: open-circuit

The o/c terminal voltage is

$$v_{o/c} = 2 \times \frac{1}{1+1} = 1V$$



Step 2: short-circuit

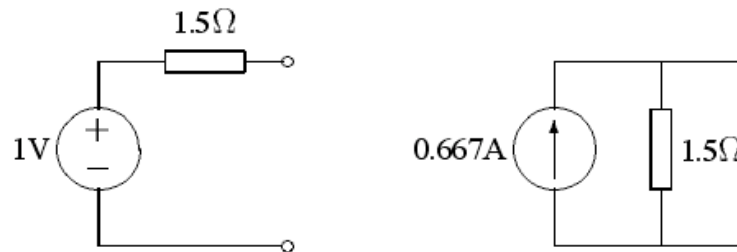
The s/c current is

$$i_{s/c} = \frac{2}{1+0.5} \times \frac{1}{2} = \frac{2}{3}A$$

Step 3: Thévenin or Norton resistance

$$R_T = R_N = \frac{v_{o/c}}{i_{s/c}} = \frac{1}{2/3} = \frac{3}{2}\Omega$$

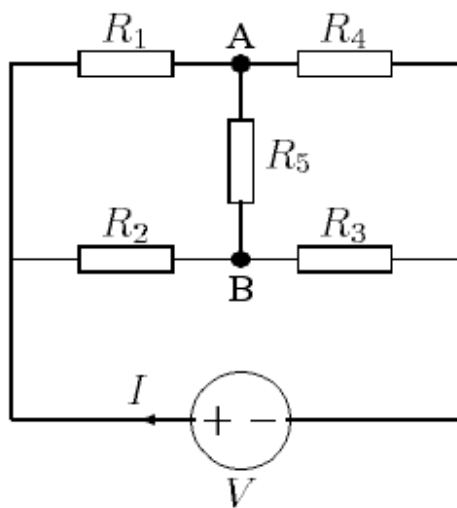
Hence, the equiv. ckts are:



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Analysis

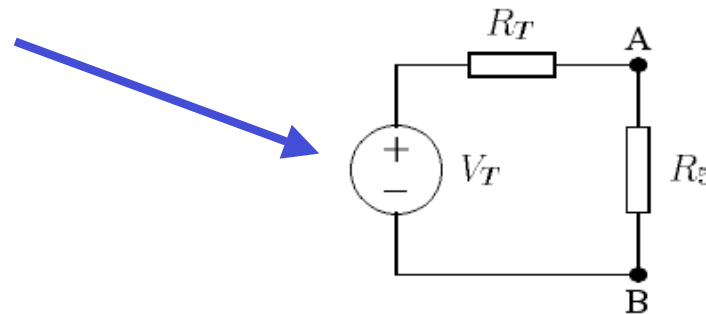
## Example — the bridge again



Problem: Find the current flowing in  $R_5$ .

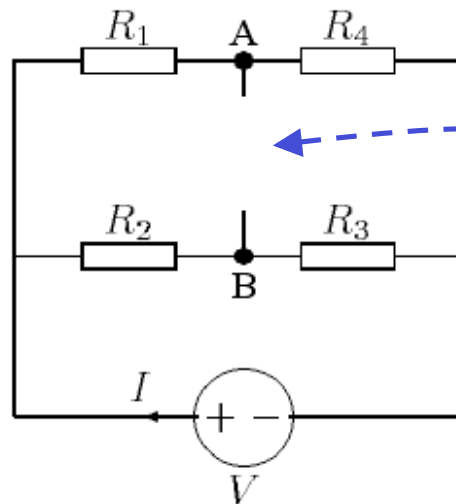
One solution is by delta-star conversion (as done before).

Another simpler method is to find the Thévenin equivalent circuit seen from  $R_5$ .





## Example — the bridge again



Step 1: open circuit

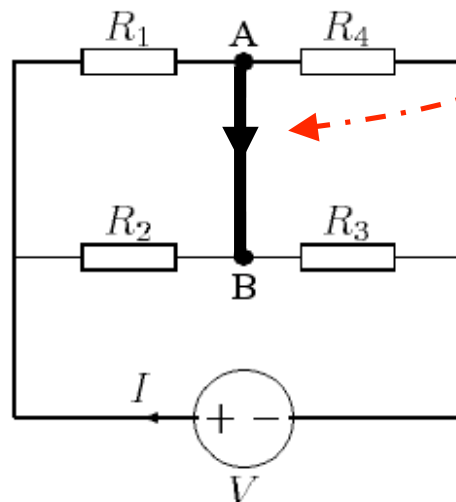
The o/c voltage across A and B is

$$v_{o/c} = V \times \left( \frac{R_4}{R_1 + R_4} - \frac{R_3}{R_2 + R_3} \right) = V_T$$

Step 2: short circuit

The s/c current is

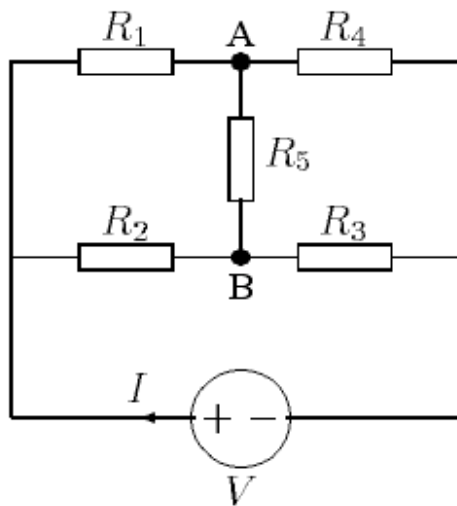
$$\begin{aligned} i_{s/c} &= (\text{current in } R_1) - (\text{current in } R_4) \\ &= I \times \left( \frac{G_1}{G_1 + G_2} - \frac{G_4}{G_3 + G_4} \right) \end{aligned}$$



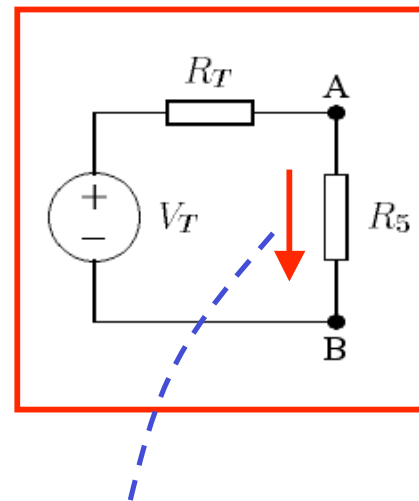
Step 3:  $R_T$

$$\begin{aligned} R_T &= \frac{v_{o/c}}{i_{s/c}} \\ &= \frac{G_1 + G_2 + G_3 + G_4}{(G_1 + G_4)(G_2 + G_3)} \\ &= (R_1 || R_4) + (R_2 || R_3) \end{aligned}$$

## Example — the bridge again



=



$$\text{Current in } R_5 = \frac{V_T}{R_5 + R_T}$$

# Maximum power transfer theorem

We consider the power dissipated by  $R_L$ .  
The current in  $R_L$  is

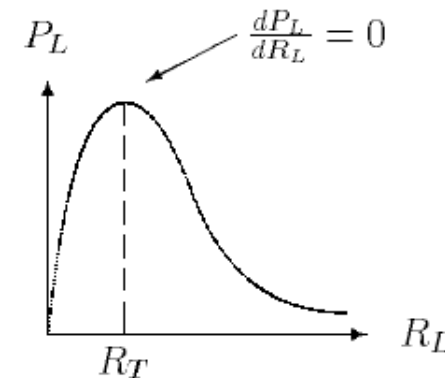
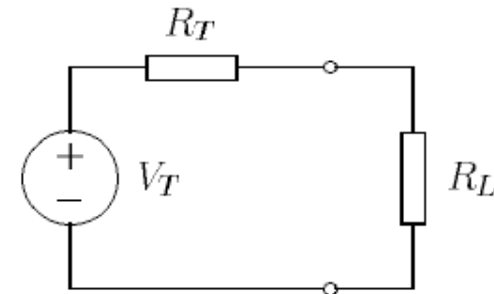
$$I = \frac{V_T}{R_T + R_L}$$

Thus, the power is

$$\begin{aligned} P_L &= I^2 R_L \\ &= \frac{V_T^2 R_L}{(R_T + R_L)^2} \end{aligned}$$

This power has a maximum, when plotted against  $R_L$ .

$$\frac{dP_L}{dR_L} = V_T^2 \frac{R_T - R_L}{(R_T + R_L)^3} = 0 \text{ gives } \boxed{R_L = R_T.}$$



## A misleading interpretation

It seems counter-intuitive that the MPT theorem suggests a maximum power at  $R_L = R_T$ .

Shouldn't maximum power occur when we have all power go to the load? That is, when  $R_T = 0$ !

**Is the MPT theorem wrong?**

Discussion: what is the condition required by the theorem?

# Systematic analysis techniques

So far, **we have solved circuits on an *ad hoc* manner.** We are able to treat circuits with parallel/series reduction, star-delta conversion, with the help of some theorems.

How about very *general arbitrary circuit styles*?

In *Basic Electronics*, you have learnt the use of MESH and NODAL methods.

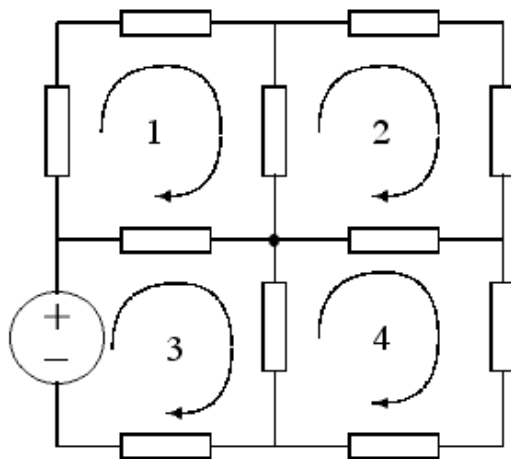
MESH — planar circuits only; solution in terms of mesh currents.

NODAL — any circuit; solution in terms of nodal voltages.

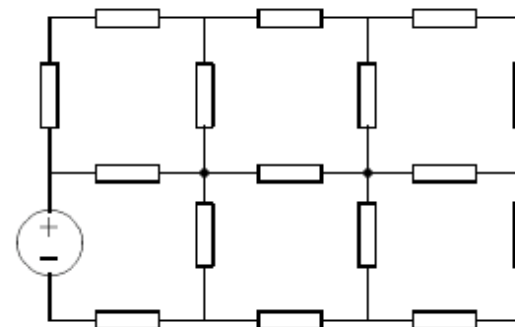
**BUT THEY ARE NOT EFFICIENT!**

# Mesh analysis (for planar circuits only)

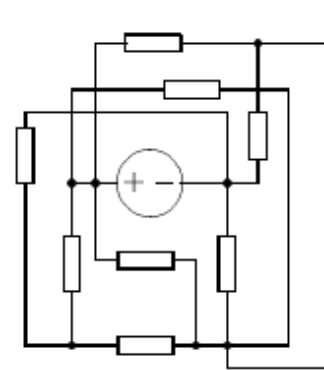
**Meshes — windows**



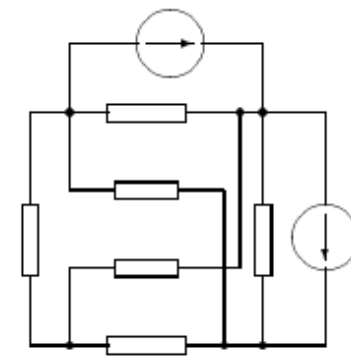
Planar or not?



(a)



(b)



(c)

# Mesh analysis

## Step 1: Define meshes and unknowns

Each window is a mesh. Here, we have two meshes. For each one, we “imagine” a current circulating around it. So, we have two such currents,  $I_1$  and  $I_2$  — unknowns to be found.

## Step 2: Set up KVL equations

$$\text{Mesh 1: } -42 + 6I_1 + 3(I_1 - I_2) = 0$$

$$\text{Mesh 2: } 3(I_2 - I_1) + 4I_2 - 10 = 0$$

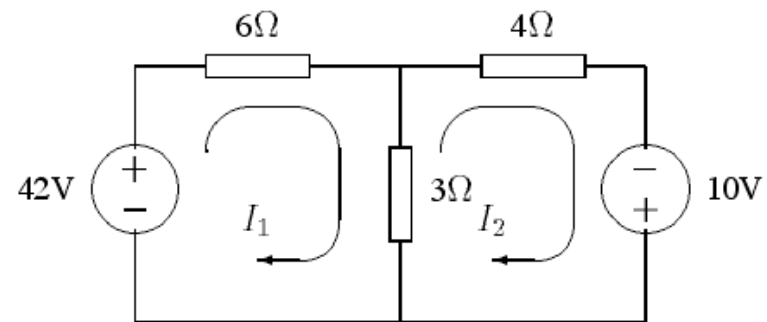
## Step 3: Simplify and solve

$$9I_1 - 3I_2 = 42$$

$$-3I_1 + 7I_2 = 10$$

which gives

$$I_1 = 6 \text{ A and } I_2 = 4 \text{ A.}$$



Once we know the mesh currents, we can find anything in the circuit!

e.g., current flowing down the  $3\Omega$  resistor in the middle is equal to  $I_1 - I_2$  ;  
current flowing up the  $42\text{V}$  source is  $I_1$  ;  
current flowing down the  $10\text{V}$  source is  $I_2$  ;  
and voltages can be found via Ohm's law.

# Mesh analysis

In general, we formulate the solution in terms of unknown mesh currents:

$$[ R ] [ I ] = [ V ] \quad \text{— mesh equation}$$

where  $[ R ]$  is the resistance matrix  
 $[ I ]$  is the unknown mesh current vector  
 $[ V ]$  is the source vector

For a short cut in setting up the above matrix equation, see [Sec. 3.2.1.2 of the textbook](#). This may be picked up in the tutorial.



## Mesh analysis — observing *superposition*

Consider the previous example. The mesh equation is given by:

$$\begin{aligned} 9I_1 - 3I_2 &= 42 \\ -3I_1 + 7I_2 &= 10 \end{aligned} \quad \text{or} \quad \begin{pmatrix} 9 & -3 \\ -3 & 7 \end{pmatrix} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix} = \begin{pmatrix} 42 \\ 10 \end{pmatrix}$$

Thus, the solution can be written as  $\begin{pmatrix} I_1 \\ I_2 \end{pmatrix} = \begin{pmatrix} 9 & -3 \\ -3 & 7 \end{pmatrix}^{-1} \begin{pmatrix} 42 \\ 10 \end{pmatrix}$

Remember what 42 and 10 are? They are the sources! The above solution can also be written as

$$\begin{aligned} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix} &= \begin{pmatrix} 9 & -3 \\ -3 & 7 \end{pmatrix}^{-1} \begin{pmatrix} 42 \\ 0 \end{pmatrix} + \begin{pmatrix} 9 & -3 \\ -3 & 7 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 10 \end{pmatrix} \\ \text{or} \quad \begin{pmatrix} I_1 \\ I_2 \end{pmatrix} &= \mathcal{R}^{-1} \begin{pmatrix} V_1 \\ 0 \end{pmatrix} + \mathcal{R}^{-1} \begin{pmatrix} 0 \\ V_2 \end{pmatrix} \\ &= \mathcal{R}^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} V_1 + \mathcal{R}^{-1} \begin{pmatrix} 0 \\ 1 \end{pmatrix} V_2 \\ &= AV_1 + BV_2 \end{aligned}$$

**SUPERPOSITION  
of two sources**

# Problem with current sources

The mesh method may run into trouble if the circuit has current source(s).

Suppose we define the unknowns in the same way, i.e.,  $I_1$ ,  $I_2$  and  $I_3$ .

**The trouble is that we don't know what voltage is dropped across the 14A source! How can we set up the KVL equation for meshes 1 and 3?**

One solution is to ignore meshes 1 and 3. Instead we look at the **supermesh** containing 1 and 3.

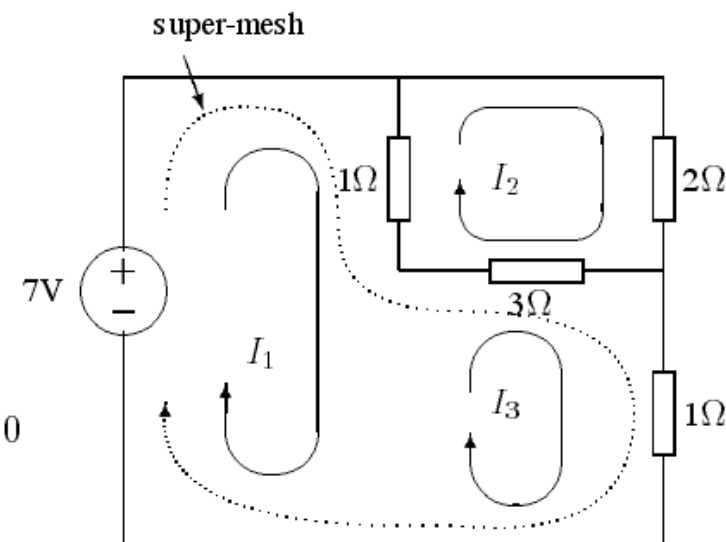
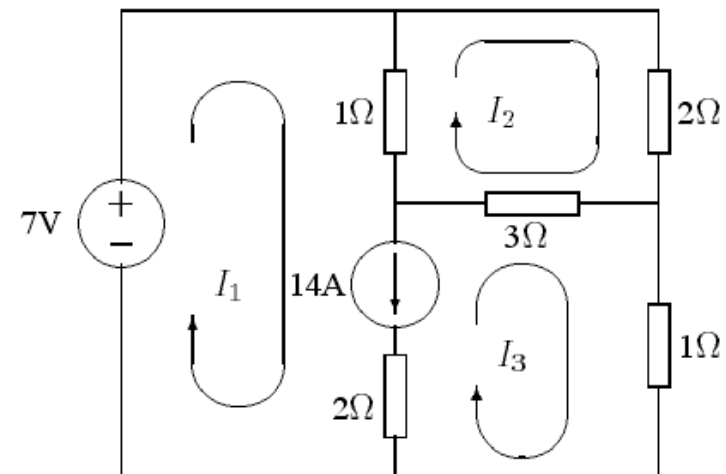
So, we set up KVL equations for mesh 2 and the supermesh:

Mesh 2:  $(I_2 - I_1) \times 1 + I_2 \times 2 + (I_2 - I_3) \times 3 = 0$

Supermesh:  $-7 + (I_1 - I_2) \times 1 + (I_3 - I_2) \times 3 + I_3 \times 1 = 0$

One more equation:  $I_1 - I_3 = 14$

Finally, solve the equations.



# Complexity of mesh method

In all cases, we see that the mesh method ends up with  $N$  equations and  $N$  unknowns, where  $N$  is the **number of meshes (windows) of the circuit.**

## **One important point:**

The mesh method is over-complex when applied to circuits with current source(s). WHY?

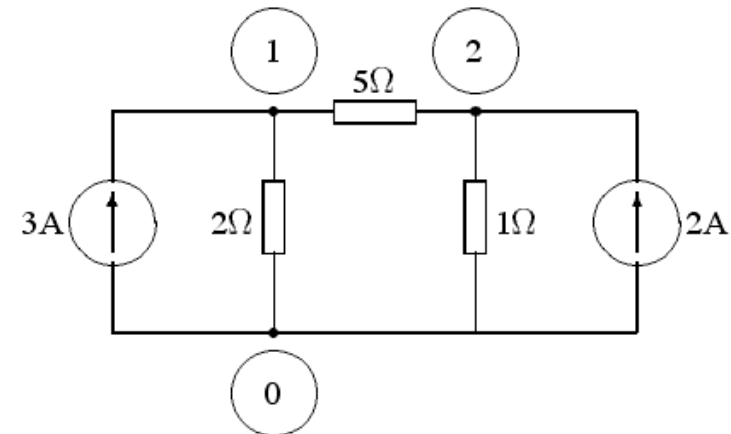
We don't need  $N$  equations for circuits with current source(s) because the currents are partly known!

In the previous example, it seems unnecessary to solve for both  $I_1$  and  $I_3$  because their difference is known to be 14! This is a waste of efforts! Can we improve it?

# Nodal analysis

## Step 1: Define unknowns

Each node is assigned a number. Choose a reference node which has zero potential. Then, each node has a voltage w.r.t. the reference node. Here, we have  $V_1$  and  $V_2$  — unknowns to be found.



## Step 2: Set up KCL equation for each node

$$\text{Node 1: } -3 + \frac{V_1}{2} + \frac{V_1 - V_2}{5} = 0$$

$$\text{Node 2: } \frac{V_2 - V_1}{5} + \frac{V_2}{1} - 2 = 0$$

## Step 3: Simplify and solve

$$\begin{bmatrix} \frac{1}{2} + \frac{1}{5} & -\frac{1}{5} \\ -\frac{1}{5} & \frac{1}{5} + 1 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

which gives  $V_1 = 5 \text{ V}$  and  $V_2 = 2.5 \text{ V}$ .

Once we know the nodal voltages, we can find anything in the circuit!

e.g., voltage across the  $5\Omega$  resistor in the middle is equal to  $V_1 - V_2$  ;  
voltage across the  $3\text{A}$  source is  $V_1$  ;  
voltage across the  $2\text{A}$  source is  $V_2$  ;  
and currents can be found via Ohm's law.

# Nodal analysis

In general, we formulate the solution in terms of unknown nodal voltages:

$$[ G ] [ V ] = [ I ] \quad \text{— nodal equation}$$

where  $[ G ]$  is the conductance matrix  
 $[ V ]$  is the unknown node voltage vector  
 $[ I ]$  is the source vector

For a short cut in setting up the above matrix equation, see [Sec. 3.3.1.2 of the textbook](#). This may be picked up in the tutorial.

## Nodal analysis — observing *superposition*

Consider the previous example. The nodal equation is given by:

$$\begin{bmatrix} \frac{1}{2} + \frac{1}{5} & -\frac{1}{5} \\ -\frac{1}{5} & \frac{1}{5} + 1 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

Thus, the solution can be written as  $\begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} \frac{7}{10} & -\frac{1}{5} \\ -\frac{1}{5} & \frac{6}{5} \end{pmatrix}^{-1} \begin{pmatrix} 3 \\ 2 \end{pmatrix}$

Remember what 3 and 2 are? They are the sources! The above solution can also be written as

$$\begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} \frac{7}{10} & -\frac{1}{5} \\ -\frac{1}{5} & \frac{6}{5} \end{pmatrix}^{-1} \begin{pmatrix} 3 \\ 0 \end{pmatrix} + \begin{pmatrix} \frac{7}{10} & -\frac{1}{5} \\ -\frac{1}{5} & \frac{6}{5} \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

or

$$\begin{aligned} \begin{pmatrix} V_1 \\ V_2 \end{pmatrix} &= \mathcal{G}^{-1} \begin{pmatrix} I_1 \\ 0 \end{pmatrix} + \mathcal{G}^{-1} \begin{pmatrix} 0 \\ I_2 \end{pmatrix} \\ &= \mathcal{G}^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} I_1 + \mathcal{G}^{-1} \begin{pmatrix} 0 \\ 1 \end{pmatrix} I_2 \\ &= AI_1 + BI_2 \end{aligned}$$

**SUPERPOSITION  
of two sources**

# Problem with voltage sources

The nodal method may run into trouble if the circuit has voltage source(s).

Suppose we define the unknowns in the same way, i.e.,  $V_1$ ,  $V_2$  and  $V_3$ .

**The trouble is that we don't know what current is flowing through the 2V source! How can we set up the KCL equation for nodes 2 and 3?**

One solution is to ignore nodes 1 and 3. Instead we look at the **supernode** merging 2 and 3.

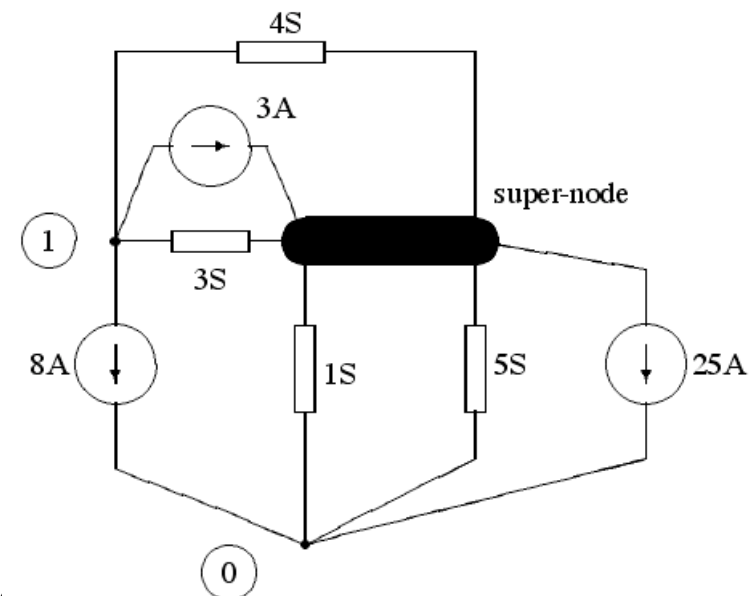
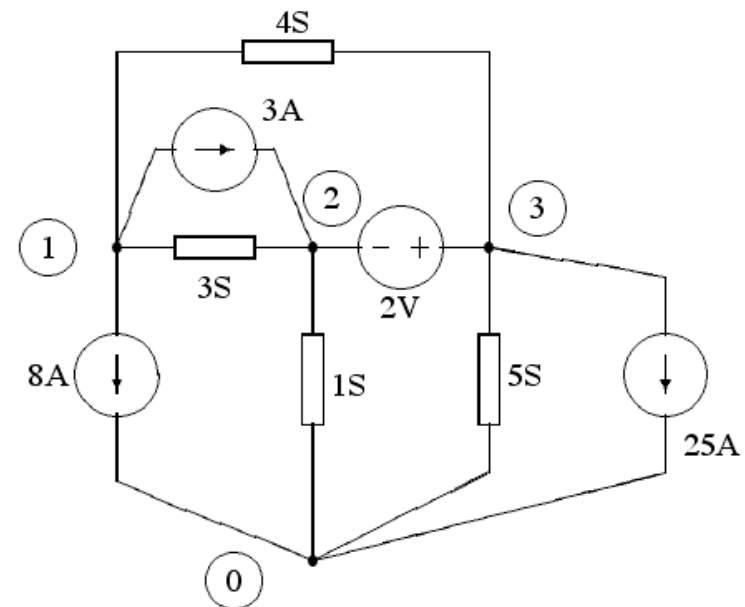
So, we set up KCL equations for node 1 and the supernode:

$$8 + (V_1 - V_2) \times 3 + 3 + (V_1 - V_3) \times 4 = 0$$

$$(V_2 - V_1) \times 3 - 3 + V_2 \times 1 + (V_3 - V_1) \times 4 + V_3 \times 5 + 25 = 0$$

One more equation:  $V_3 - V_2 = 2$

Finally, solve the equations.



# Complexity of nodal method

In all cases, we see that the mesh method ends up with  $N$  equations and  $N$  unknowns, where  $N$  is the **number of nodes of the circuit minus 1**.

## **One important point:**

The nodal method is over-complex when applied to circuits with voltage source(s). WHY?

We don't need  $N$  equations for circuits with voltage source(s) because the node voltages are partly known!

In the previous example, it seems unnecessary to solve for both  $V_2$  and  $V_3$  because their difference is known to be 2! This is a waste of efforts! Can we improve it?



# Final note on superposition

Superposition is a consequence of linearity.

We may conclude that for any linear circuit, any voltage or current can be written as linear combination of the sources.

Suppose we have a circuit which contains two voltage sources  $V_1$ ,  $V_2$  and  $I_3$ . And, suppose we wish to find  $I_x$ .

Without doing anything, we know for sure that the following is correct:

$$I_x = a V_1 + b V_2 + c I_3$$

where a, b and c are some constants.

**Is this property useful?**  
**Can we use this property for analysis?**

**We may pick this up in the tutorial.**

